Electric Cylinders

**Electric Cylinder**

It can be operated like an air cylinder.

**Series LZB**

**Series LZC**

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### Directional Control Driver for Electric Cylinder

Directional control driver like a solenoid valve

- Able to control the stroke with only ON/OFF signals.
- A current control protects the driver/motor from burning out.
- Able to control with only 3 different types of input signals.

1. Directional control (A-PHASE)
2. Output ON/OFF (ON)
3. Thrust selection (SET)

Can be operated manually.

**Model** | **Max. thrust** | **Max. speed** | **Lead screw** | **Stroke**
---|---|---|---|---
LZB | 196 N | 200 mm/s | Slide screw: ø8, ø12 | 25, 40, 50
LZC | **Max. thrust** | **Max. speed** | **Lead screw** | **Stroke**
---|---|---|---|---
196 N | 200 mm/s | Slide screw: ø8, ø12 | Lead: 2, 6, 12 | 25, 40, 50
100, 200 | 100, 200 | 100, 200 | 100, 200

---
Features 1

- **PLC (Terminal box type)** (Supplied by customer)
- **Directional control driver for electric cylinder** Series LC3F2
- **24 VDC power supply** (Supplied by customer)
- **Auto switch** D-M9 □ (Optional)
- **Terminal box** (Supplied by customer)
- **Electric cylinder** Series LZB/LZC
- **AC power supply** Noise filter, Insulator, Relay, etc. (Supplied by customer)

Cables:
- **Cable for control terminal** LC3F2-1-C2-□-1 (Optional) (See page 20.)
- **Cable for motor output terminal** LC3F2-1-C3-□-1 (Optional) (See page 20.)
- **Cable for power supply terminal** LC3F2-1-C1-□-1 (Optional) (See page 20.)
Series LZB/LZC
Model Selection

Note) These graphs are made using actual data. Therefore these graphs are to be used as a reference and are not a guarantee of product’s performance in any case. The graphs may change depending on the operating condition or environment.

Motion of Pressing Force

Model selection condition 1)
Used as a force-pressing, 50 N or greater pressing

Model selection result 1)
From Graph 1, LZB/C\(\text{3}\)'s lead 2 is applicable. (Pressing force: 80 N)

Graph 1
LZ\(\text{3}\): [Speed-Thrust] Relationship Graph

Speed-Thrust Graph

LZ\(\text{3}\)

Model selection condition 1)
Used as a force-pressing, 50 N or greater pressing

Model selection result 1)
From Graph 1, LZB/C\(\text{3}\)'s lead 2 is applicable. (Pressing force: 80 N)

LZ\(\text{5}\)

Transfer

Model selection condition 2)
Used as a transfer. 60 N transfer thrust and 40 mm/s transfer speed are required.

Model selection result 2)
From Graph 2, LZB/C\(\text{5}\)'s lead 6 mm and lead 12 mm are applicable. But, speed at the end with 60 N load will be 100 mm/s for lead 6 mm and 60 mm/s for lead 12 mm. Select a suitable product in accordance with the customer’s equipment.

Graph 2
LZ\(\text{5}\): [Speed-Thrust] Relationship Graph
Electric Cylinder
Series **LZB**

How to Order

**With auto switch**

**LZB** B 3 L 100 A 3

**LDZB** B 3 L 100 A 3 M9B

- **Mounting style**
  - B: Basic style
  - L: Axial foot style
  - F: Rod flange style
  - U: Rod trunnion style

- **Cylinder size**
  - 3: Equivalent to ø16 cylinder
  - 5: Equivalent to ø25 cylinder

Note: Equivalent to 0.4 MPa, theoretical output (lead 2)

- **Thread lead (mm)**
  - L: Lead 2
  - M: Lead 6
  - H: Lead 12

- **Stroke (mm)**
  - Refer to “Standard stroke” table.

**Standard Stroke**

<table>
<thead>
<tr>
<th>Cylinder size</th>
<th>Standard stroke (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3, 5</td>
<td>25, 40, 50, 100, 200</td>
</tr>
</tbody>
</table>

- Other intermediate strokes can be manufactured upon receipt of order. (Maximum manufacturable stroke: 200 mm)

**Applicable Auto Switches**

<table>
<thead>
<tr>
<th>Type</th>
<th>Special function</th>
<th>Electrical entry</th>
<th>Indexing type</th>
<th>Wiring (Output)</th>
<th>Load voltage</th>
<th>Auto switch model</th>
<th>Lead wire length (m)</th>
<th>Pre-wired connector</th>
<th>Applicable load</th>
</tr>
</thead>
<tbody>
<tr>
<td>Solid state switch</td>
<td>—</td>
<td>Grommet</td>
<td>Yes</td>
<td>3-wire (NPN)</td>
<td>5 V, 12 V</td>
<td>M9N</td>
<td>●</td>
<td>●</td>
<td>4-loop IC</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>3-wire (PNP)</td>
<td></td>
<td>M9P</td>
<td>●</td>
<td>●</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2-wire</td>
<td></td>
<td>M9B</td>
<td>●</td>
<td>●</td>
<td>—</td>
</tr>
</tbody>
</table>

- Lead wire length symbols: 0.5 m (Nil) (Example) M9N
  - 3 m L M9NL
  - 5 m Z M9NZ

- Solid state switches marked “●” are produced upon receipt of order.

---

**Note:**

- Equivalent to ø16 cylinder
- Equivalent to ø25 cylinder
- Maximum stroke: 150 mm
- Thread lead (lead 2 mm) only
- Rod end male thread is shipped together.
**Specific Product Precautions**

1. Do not apply any load to the rod end of the LZB series. When applying a load, use a guide to avoid the load from being applied to the rod end.

2. Auto switch mounting

   There are 4 markings on the outside surface of the cylinder tube, indicating the auto switch installation range. Mount the auto switches within the range shown below.

   ![Auto switch installation range diagram]

   * Refer to page 15 for information on mounting an auto switch.

---

**Specifications**

<table>
<thead>
<tr>
<th>Model</th>
<th>LZB3L</th>
<th>LZB3M</th>
<th>LZB3H</th>
<th>LZB5L</th>
<th>LZB5M</th>
<th>LZB5H</th>
</tr>
</thead>
<tbody>
<tr>
<td>Size</td>
<td>3 (Equivalent to ø16 cylinder) Note 1</td>
<td>5 (Equivalent to ø25 cylinder) Note 1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lead screw</td>
<td>Thread diameter Ø8</td>
<td>Ø12</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Lead (mm)</td>
<td>2</td>
<td>6</td>
<td>12</td>
<td>2</td>
<td>6</td>
</tr>
<tr>
<td>Rated speed with no load (mm/s)</td>
<td>33</td>
<td>100</td>
<td>200</td>
<td>33</td>
<td>100</td>
<td>200</td>
</tr>
<tr>
<td>Rated thrust (N)</td>
<td>80</td>
<td>43</td>
<td>24</td>
<td>196</td>
<td>117</td>
<td>72</td>
</tr>
<tr>
<td>Stroke (mm)</td>
<td>25, 40, 50, 100, 200</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Main body (kg)*</td>
<td>0.67 + (0.07/50 stroke)</td>
<td>1.74 + (0.16/50 stroke)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operating ambient temperature (°C)</td>
<td>5 to 40 (with no condensation)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Tolerance of rod end thread</td>
<td>JIS class 2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Allowable tolerance of stroke</td>
<td>±0.1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Motor</td>
<td>DC motor</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Applicable directional control driver model</td>
<td>LC3F212-5A3□</td>
<td>LC3F212-5A5□</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Applicable auto switch model</td>
<td>D-M9N, M9P, M9B</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note 1) Equivalent to 0.4 MPa, theoretical output (lead 2)
Note 2) In the table speeds are shown without a load, as rated speed, and thrusts are shown as rated thrust based on the pressure force.
Note 3) Speed will vary as they are affected by a load. Refer to page 1 for model selection.

* Refer to page 13 for mounting bracket weight.
**Dimensions**

Note) Grounding must be performed. For details, refer to the back of page 2.

**L(D)ZBB3**

- Hexagon width across flats 13
- Stroke 1
- M20 x 1.5
- M6 x 1.0
- Thread length 8

**Axial foot style/L(D)ZBL3**

- Hexagon width across flats 26
- Hexagon width across flats 13
- M20 x 1.5
- M6 x 1.0
- Thread length 8

**Rod flange style/L(D)ZBF3**

- Hexagon width across flats 13
- Stroke
- M20 x 1.5
- M6 x 1.0
- Thread length 8
- Motor side mounting nut (Part no.: LZ NT30)
- Hexagon width across flats 27
- Width across flats 34
- M30 x 1.5

- Lead wire
  - UL1007 AWG22 (Red-Blue)
  - Motor side mounting nut
  - Rod end male thread: L

- J.S.T. Mfg Co., Ltd.-made, ring terminal insulated with nylon N1.25-M4 or equivalent
- Lead wire
  - UL1007 AWG22 (Red-Blue)

- When extended
  - Rod end nut
    - (Part no.: N1 U1 A)
  - Rod side mounting nut
    - (Part no.: SN 020B)
  - Hexagon width across flats 8
  - Depth 3 (For GND connection) Note)

- When retracted
  - M6 x 1.0
  - Rod side mounting nut
    - (Part no.: SN 020B)
  - Hexagon width across flats 26
  - Motor side mounting nut
    - (Part no.: LZ NT30)
  - Hexagon width across flats 34
  - Lead wire
    - UL1007 AWG22 (Red-Blue)

- Stroke
  - +1
  - 0

- Axial foot style/L(D)ZBL3

- Rod flange style/L(D)ZBF3

- J.S.T. Mfg Co., Ltd.-made, ring terminal insulated with nylon N1.25-M4 or equivalent

- Lead wire
  - UL1007 AWG22 (Red-Blue)

- When extended
  - Rod end nut
    - (Part no.: N1 U1 A)
  - Rod side mounting nut
    - (Part no.: SN 020B)
  - Hexagon width across flats 8
  - Depth 3 (For GND connection) Note)

- When retracted
  - M6 x 1.0
  - Rod side mounting nut
    - (Part no.: SN 020B)
  - Hexagon width across flats 26
  - Motor side mounting nut
    - (Part no.: LZ NT30)
  - Hexagon width across flats 34
  - Lead wire
    - UL1007 AWG22 (Red-Blue)

- Stroke
  - +1
  - 0

- Axial foot style/L(D)ZBL3

- Rod flange style/L(D)ZBF3
**Dimensions**

**Rod trunnion style/L(D)ZBU3□**

<table>
<thead>
<tr>
<th>Dimensions</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>ø32</td>
<td>52</td>
</tr>
<tr>
<td>ø16</td>
<td>10</td>
</tr>
<tr>
<td>ø14</td>
<td>12</td>
</tr>
<tr>
<td>Width across flats 26</td>
<td>108.5 + Stroke</td>
</tr>
<tr>
<td>Hexagon width across flats 27</td>
<td>216.5 + Stroke</td>
</tr>
<tr>
<td>Hexagon width across flats 13</td>
<td>156.5</td>
</tr>
<tr>
<td>Hexagon width across flats 26</td>
<td>19</td>
</tr>
<tr>
<td>ø38</td>
<td>43.5</td>
</tr>
<tr>
<td>M30 x 1.5</td>
<td>10</td>
</tr>
<tr>
<td>Width across flats 27</td>
<td>43.5</td>
</tr>
</tbody>
</table>

---

**Caution for using a trunnion bracket**

**In the event of mounting a trunnion bracket, fix it to the position illustrated below before using.**

- **Auto switch installation range**
- **Marking**
- **4 markings**

* Conditions for using a trunnion bracket are as follows:
  - Maximum stroke: 150 mm
  - Thread lead L (lead 2 mm) only
**Dimensions**  
Note: Grounding must be performed. For details, refer to the back of page 2.

### L(D)ZBB5

- **Rod side mounting nut** (Part no.: SN 040B)  
  - M10 x 1.25  
  - Thread length 12

- **Hexagon width across flats**  
  - 21

- **Width across flats**  
  - 36

- **Motor side mounting nut** (Part no.: NT-03)  
  - M32 x 2

- **Hexagon width across flats**  
  - 41

- **Width across flats**  
  - 38

- **Motor side mounting nut** (Part no.: N1 140)  
  - M45 x 1.5

- **Hexagon width across flats**  
  - 41

- **Width across flats**  
  - 38

- **Lead wire**  
  - UL1007 AWG22 (Red-Blue)

- **Thread length**  
  - 12

- **Depth**  
  - 3 (For GND connection) 

### L(D)ZBL5

- **Rod side mounting nut** (Part no.: SN 040B)  
  - M10 x 1.25  
  - Thread length 12

- **Hexagon width across flats**  
  - 21

- **Width across flats**  
  - 36

- **Motor side mounting nut** (Part no.: L N1 40)  
  - M45 x 1.5

- **Lead wire**  
  - UL1007 AWG22 (Red-blue)

- **Thread length**  
  - 12

- **Depth**  
  - 3 (For GND connection)

### L(D)ZBF5

- **Rod side mounting nut**  
  - M10 x 1.25  
  - Thread length 12

- **Hexagon width across flats**  
  - 21

- **Width across flats**  
  - 36

- **Motor side mounting nut**  
  - M32 x 2

- **Hexagon width across flats**  
  - 41

- **Width across flats**  
  - 38

- **Lead wire**  
  - UL1007 AWG22 (Red-Blue)

- **Thread length**  
  - 12

- **Depth**  
  - 3 (For GND connection)
Caution for using a trunnion bracket

In the event of mounting a trunnion bracket, fix it to the position illustrated below before using.

*Conditions for using a trunnion bracket are as follows:
  - Maximum stroke: 150 mm
  - Thread lead L (lead 2 mm) only
**Electric Cylinder Series LZC**

### How to Order

#### LZC

**With auto switch**

<table>
<thead>
<tr>
<th>Cylinder size</th>
<th>Standard stroke (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3, 5</td>
<td>25, 40, 50, 100, 200</td>
</tr>
</tbody>
</table>

**Mounting style**

- B: Basic style
- L: Axial foot style

**Cylinder size**

- 3: Equivalent to ø16 cylinder
- 5: Equivalent to ø25 cylinder

**Thread lead (mm)**

- L: Lead 2
- M: Lead 6
- H: Lead 12

**Stroke (mm)**

Refer to “Standard stroke” table.

**Motor type**

- A: DC motor

### Standard Stroke

| Cylinder size | Standard stroke (mm) *
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>3, 5</td>
<td>25, 40, 50, 100, 200</td>
</tr>
</tbody>
</table>

*Other intermediate strokes can be manufactured upon receipt of order.*

**With auto switch**

- Number of auto switches
  - Nil: 2 pcs.
  - S: 1 pc.
  - n: n

**Auto switch**

- Nil: Without auto switch (Built-in magnet)
- Refer to the table below for auto switch model numbers.
- The auto switch is not mounted and is supplied separately at the time of shipment.

**Cover specification**

- Nil: None
- H: Partially covered
- F: Fully covered

**Mod end thread**

- Nil: Female
- L: Male

**Motor size**

- 3: Applicable cylinder size 3
- 5: Applicable cylinder size 5

---

**Applicable Auto Switches**

For detailed auto switch specifications, refer to page 16 through to 18.

<table>
<thead>
<tr>
<th>Type</th>
<th>Special function</th>
<th>Electrical entry</th>
<th>Indicator light</th>
<th>Wiring (Output)</th>
<th>Load voltage</th>
<th>Auto switch model</th>
<th>Lead wire length (m)</th>
<th>Pre-wired connector</th>
<th>Applicable load</th>
</tr>
</thead>
<tbody>
<tr>
<td>Solid state switch</td>
<td>—</td>
<td>Grommet</td>
<td>Yes</td>
<td>3-wire (NPN)</td>
<td>24 V</td>
<td>5 V 12 V</td>
<td>M9N</td>
<td>0.5 (Nil) 3 (L) 2 (Z)</td>
<td>IC circuit</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>3-wire (PNP)</td>
<td></td>
<td></td>
<td>M9P</td>
<td></td>
<td>Relays</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>2-wire</td>
<td></td>
<td></td>
<td>M9B</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

* Load wire length symbols: JS: Nil (Example: M9N 2 m)

- Solid state switches marked "JS" are produced upon receipt of order.
### Specifications

<table>
<thead>
<tr>
<th>Model</th>
<th>LZC3L</th>
<th>LZC3M</th>
<th>LZC3H</th>
<th>LZC5L</th>
<th>LZC5M</th>
<th>LZC5H</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Size</strong></td>
<td>3 (Equivalent to ø16 cylinder)</td>
<td>3 (Equivalent to ø16 cylinder)</td>
<td>5 (Equivalent to ø25 cylinder)</td>
<td>5 (Equivalent to ø25 cylinder)</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Lead screw</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Thread diameter</td>
<td>Ø8</td>
<td>Ø8</td>
<td>Ø12</td>
<td>Ø12</td>
<td>Ø12</td>
<td>Ø12</td>
</tr>
<tr>
<td>Lead (mm)</td>
<td>2</td>
<td>2</td>
<td>12</td>
<td>12</td>
<td>12</td>
<td>12</td>
</tr>
<tr>
<td>Rated speed with no load (mm/s)</td>
<td>33</td>
<td>100</td>
<td>200</td>
<td>33</td>
<td>100</td>
<td>200</td>
</tr>
<tr>
<td>Rated thrust (N)</td>
<td>80</td>
<td>43</td>
<td>24</td>
<td>196</td>
<td>117</td>
<td>72</td>
</tr>
<tr>
<td>Stroke (mm)</td>
<td>25, 40, 50, 100, 200</td>
<td>25, 40, 50, 100, 200</td>
<td>25, 40, 50, 100, 200</td>
<td>25, 40, 50, 100, 200</td>
<td>25, 40, 50, 100, 200</td>
<td>25, 40, 50, 100, 200</td>
</tr>
<tr>
<td>Main body (kg)*</td>
<td>0.72 + (0.03/50 stroke)</td>
<td>1.72 + (0.16/50 stroke)</td>
<td>0.1</td>
<td>0.24</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lateral load for rod end (at maximum stroke) (kg)</td>
<td>0.1</td>
<td>0.24</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operating ambient temperature (°C)</td>
<td>5 to 40 (with no condensation)</td>
<td>5 to 40 (with no condensation)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Tolerance of rod end thread</td>
<td>JIS class 2</td>
<td>JIS class 2</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Allowable tolerance of stroke</td>
<td>±0.1</td>
<td>±0.1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Motor</td>
<td>DC motor</td>
<td>DC motor</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Applicable directional control driver model</td>
<td>LC3F212-5A3□</td>
<td>LC3F212-5A5□</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Applicable auto switch model</td>
<td>D-M9N, M9P, M9B</td>
<td>D-M9N, M9P, M9B</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note 1:** Equivalent to 0.4 MPa, theoretical output (lead 2)

**Note 2:** In the table speeds are shown without a load, as rated speed, and thrusts are shown as rated thrust based on the pressure force.

**Note 3:** Speed will vary as they are affected by a load. Refer to page 1 for model selection.

+ Refer to page 13 for mounting bracket weight.

### Allowable Lateral Load for Rod End

![Graph showing allowable lateral load for rod end (N) vs. stroke (mm)]
Series LZC

Dimensions
Note) Grounding must be performed. For details, refer to the back of page 2.

L(D)ZCB3

Cover specification

Fully covered: F
Partially covered: H

Axial foot style: L
Dimensions  Note) Grounding must be performed. For details, refer to the back of page 2.

L(D)ZCB5□

Axial foot style: L

Foot (Rod cover side)  Foot (Housing side)

Cover specification

Note) L(D)ZCB5□/L50132

Electric Cylinder Series LZC
LZB/C Vertical Application Specifications

Some of the LZ series can be used in vertical applications. However, please check before using vertically.

Never apply a force exceeding the prescribed force. When a force exceeding the transfer thrust is applied, the cylinder and directional control driver (LC3F2) may be damaged.

Model which can be used vertically

- L(D)ZB/L50132 3L-
- L(D)ZC/L50132 3L-
- L(D)ZB/L50132 5L-
- L(D)ZC/L50132 5L-

Specifications

<table>
<thead>
<tr>
<th>Model</th>
<th>L(D)ZB3L</th>
<th>L(D)ZC3L</th>
<th>L(D)ZB5L</th>
<th>L(D)ZC5L</th>
</tr>
</thead>
<tbody>
<tr>
<td>Speed (mm/s)</td>
<td>P.1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Transfer thrust (Vertically) (N)</td>
<td>40</td>
<td></td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>Holding force* (N)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Standard stroke (mm)</td>
<td>25, 40, 50, 100, 200</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operating ambient temperature (°C)</td>
<td>5 to 40 (with no condensation)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Motor</td>
<td>DC motor</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Applicable directional control driver model</td>
<td>LC3F212-5A3</td>
<td>LC3F212-5A5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Applicable auto switch model</td>
<td>D-M9N, D-M9P, D-M9B</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

* Holding force

Holding force means the force which cannot be dropped even if a load should be applied vertically when a cylinder is stopped. Therefore, for example, holding is not possible when turning off the power supply once a cylinder has been activated. Additionally, a load may be dropped due to external impacts or vibrations.
## Accessory Bracket

### Mounting nut

<table>
<thead>
<tr>
<th>Name</th>
<th>Part no.</th>
<th>Applicable series</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>d</th>
<th>H</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Rod side mounting nut</td>
<td>SN-020B</td>
<td>LZB3</td>
<td>26</td>
<td>30</td>
<td>25.5</td>
<td>30</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>Motor side mounting nut</td>
<td>LZ-NT30</td>
<td>LZB3</td>
<td>38</td>
<td>42</td>
<td>38</td>
<td>42</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>Rod side mounting nut</td>
<td>SN-040B</td>
<td>LZB5</td>
<td>41</td>
<td>47.3</td>
<td>40.5</td>
<td>47.3</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>Motor side mounting nut</td>
<td>LZ-NT45</td>
<td>LZB5</td>
<td>60</td>
<td>64</td>
<td>60</td>
<td>64</td>
<td>10</td>
<td></td>
</tr>
</tbody>
</table>

### Rod end nut

<table>
<thead>
<tr>
<th>Name</th>
<th>Part no.</th>
<th>Applicable series</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>d</th>
<th>H</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Rod end nut</td>
<td>NT-015A</td>
<td>LZC-LR3</td>
<td>10</td>
<td>11.5</td>
<td>9.8</td>
<td>11.5</td>
<td>6</td>
<td></td>
</tr>
<tr>
<td></td>
<td>NT-03</td>
<td>LZC-LR5</td>
<td>17</td>
<td>19.6</td>
<td>16.5</td>
<td>19.6</td>
<td>6</td>
<td></td>
</tr>
</tbody>
</table>

### Mounting Bracket/Part No.

#### Rod side foot

<table>
<thead>
<tr>
<th>Series</th>
<th>LZB3</th>
<th>LZB5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rod side foot</td>
<td>LZB-LR3 (64 g)</td>
<td>LZB-LR5 (112 g)</td>
</tr>
<tr>
<td>Motor side foot</td>
<td>LZB-LM3 (64 g)</td>
<td>LZB-LM5 (126 g)</td>
</tr>
<tr>
<td>Flange</td>
<td>LZB-F3 (40 g)</td>
<td>LZB-F5 (120 g)</td>
</tr>
<tr>
<td>Rod side trunnion</td>
<td>CM-T020B (40 g)</td>
<td>CM-T040B (100 g)</td>
</tr>
</tbody>
</table>

#### Motor side foot

<table>
<thead>
<tr>
<th>Series</th>
<th>LZC3</th>
<th>LZC5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rod side foot</td>
<td>LZC-LR3 (21 g)</td>
<td>LZC-LR5 (71 g)</td>
</tr>
<tr>
<td>Motor side foot</td>
<td>LZC-LM3 (10 g)</td>
<td>LZC-LM5 (27 g)</td>
</tr>
</tbody>
</table>

( ) : Weight for bracket

Note) Bolt needs to be supplied by customer.
**Auto Switch Proper Mounting Position for Stroke End Detection and Mounting Height**

**Solid state auto switch**

D-M9

**LDZB**

<table>
<thead>
<tr>
<th>Auto Switch Mounting Position/Height</th>
<th>Operating Range of Auto Switch *</th>
<th>Minimum Stroke for Auto Switch Mounting</th>
</tr>
</thead>
<tbody>
<tr>
<td>Model</td>
<td>A</td>
<td>B</td>
</tr>
<tr>
<td>LDZB3</td>
<td>20</td>
<td>19</td>
</tr>
<tr>
<td>LDZB5</td>
<td>33</td>
<td>33</td>
</tr>
</tbody>
</table>

* The operating range is a guide including hysteresis, but is not guaranteed. There may be substantial variation depending on the surrounding environment (assuming approximately ±30% dispersion).

**LDZC**

<table>
<thead>
<tr>
<th>Auto Switch Mounting Position for Stroke End Detection</th>
<th>Operating Range of Auto Switch *</th>
<th>Minimum Stroke for Auto Switch Mounting</th>
</tr>
</thead>
<tbody>
<tr>
<td>Model</td>
<td>A1</td>
<td>A2</td>
</tr>
<tr>
<td>LDZC3</td>
<td>4.5</td>
<td>17.5</td>
</tr>
<tr>
<td>LDZC5</td>
<td>7</td>
<td>57</td>
</tr>
</tbody>
</table>

* The operating range is a guide including hysteresis, but is not guaranteed. There may be substantial variation depending on the surrounding environment (assuming approximately ±30% dispersion).
Mounting and Moving Auto Switches (Series LDZB Only)

Mounting the Auto Switch
1. Attach a switch bracket to the switch holder.
   (Fit the switch bracket to the switch holder.)
2. Mount an auto switch mounting band to the cylinder tube.
3. Set the switch holder between the reinforcing plates of the band mounted to the cylinder.
4. Insert a switch mounting screw in the hole of the reinforcing plate through the switch holder, and thread it into the other plate. Tighten the screw temporarily.
5. Remove the set screw attached to the auto switch.
6. Attach a switch spacer to the auto switch.
7. Insert the auto switch with the switch spacer from the back of the switch holder.
   (Insert the auto switch with an angle of approximately 10 to 15°. See figure 1.)
8. To secure the auto switch, tighten the switch mounting screw with the specified torque (0.8 N•m to 1.0 N•m).

Adjusting the Switch Position
1. Unloosen the switch mounting screw 3 turns to adjust the switch set position.
2. Tighten the screw as described above (8.) after adjustment.

Removing the Auto Switch
1. Remove the switch mounting screw from the switch holder.
2. Move the switch back towards the position where it stops at the lead wire side.
3. Hold up the lead wire side of the switch at the angle of around 45°.
4. Maintain the angle, and pull back the switch obliquely at the same angle.

Specific Product Precautions

Be sure to read before handling. Refer to “SMC Best Pneumatics 2004” catalog Vol. 6/7/8/9/10/11/12 for Safety Instructions and Auto Switches Precautions.

Caution

1. Mount the auto switches at the center of the operating range.
   Check ON and OFF points before setting auto switches so that positions can be detected at the center of the operating range.
   If mounted at the end of the operating range, the signal detection will be unstable.

2. Be aware of the environment temperature and thermal cycle.
   Operate auto switches and auto switch cylinders within the operating temperature range.
   The reliability of the auto switches may be adversely affected, especially, when they are exposed to thermal shock, severe temperature and humidity cycle etc.

3. Be aware of the suitability of oil, chemicals etc.
   Resin and rubber materials are used for the auto switches and switch mounting brackets. Therefore, if there are chemicals such as oil or organic solvents in the environment, the resin and rubber materials may be adversely affected.

4. During maintenance, securely tighten the switch mounting screws periodically.
   Use switch mounting brackets with the proper tightening torque. In addition, securely tighten the switch mounting screws periodically.

5. Be careful not to pull or strain the lead wires.
   Be careful not to apply excess tensile force (over 10 N) to the auto switches. Also, adjust the position of the auto switches by sufficiently loosening the screws (3 turns or more).

6. Do not use the auto switches in environments with strong vibration and impact.
   Do not use the auto switches in environments where excess vibration and impact force outside of the specifications are applied.

7. Be sure to use a switch spacer and a switch bracket.
   Confirm that a switch spacer is mounted to the end of the auto switch before fastening the auto switch. If the switch bracket is not mounted, the auto switch may move after installation.
### Auto Switch Common Specifications

<table>
<thead>
<tr>
<th>Type</th>
<th>Solid state switch</th>
</tr>
</thead>
</table>
| Leakage current     | 3-wire: 100 µA or less  
                     | 2-wire: 0.8 mA or less |
| Operating time      | 1 ms or less       |
| Impact resistance   | 1000 m/s²          |
| Insulation resistance| 50 MΩ or more at 500 VDC Mega (between lead wire and case) |
| Withstand voltage   | 1000 VAC for 1 minute (between lead wire and case) |
| Ambient temperature | –10 to 60°C        |
| Enclosure           | IEC529 standard IP67, JIS C 0920 waterproof construction |

### Lead Wire Length

<table>
<thead>
<tr>
<th>Lead wire length indication (Example)</th>
<th>D-M9P</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lead wire length</td>
<td>L</td>
</tr>
<tr>
<td>Nil</td>
<td>0.5 m</td>
</tr>
<tr>
<td>L</td>
<td>3 m</td>
</tr>
<tr>
<td>Z</td>
<td>5 m</td>
</tr>
</tbody>
</table>

Note 1) Applicable auto switch with 5 m lead wire “Z” Solid state switch: Manufactured upon receipt of order as standard.

### Auto Switch Hysteresis

The hysteresis is the difference between the position of the auto switch as it turns “on” and as it turns “off.” A part of operating range (one side) includes this hysteresis.

Note) Hysteresis may fluctuate due to the operating environment. Contact SMC if hysteresis causes an operational problem.
Series Lzb/Lzc
Auto Switch
Connections and Examples

Basic Wiring

Solid state 3-wire, NPN

Solid state 3-wire, PNP

2-wire (Solid state)

(Power supplies for switch and load are separate)

Example of Connection to PLC (Programmable Logic Controller)

- Sink input specifications
  3-wire, NPN

- Source input specifications
  3-wire, PNP

2-wire

Example of AND (Serial) and OR (Parallel) Connection

- 3-wire
  AND connection for NPN output (using relays)
  AND connection for NPN output (performed with switches only)

- 2-wire
  2-wire with 2-switch AND connection
  2-wire with 2-switch OR connection

Example of Connection to PLC (Programmable Logic Controller)

Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

Example of AND (Serial) and OR (Parallel) Connection

Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

Example of Connection to PLC (Programmable Logic Controller)

Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

Example of Connection to PLC (Programmable Logic Controller)

Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

Example of Connection to PLC (Programmable Logic Controller)

Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.
Solid State Switch: Direct Mounting Style
D-M9N/D-M9P/D-M9B

Grommet
- 2-wire load current is reduced (2.5 to 40 mA)
- Lead-free
- UL certified (style 2844) lead cable is used.

Caution
Operating Precautions
Fix the switch with the existing screw installed on the switch body. The switch may be damaged if a screw other than the one supplied, is used.

Auto Switch Internal Circuit

D-M9N

D-M9P

D-M9B

Auto Switch Specifications

<table>
<thead>
<tr>
<th>Auto switch part no.</th>
<th>D-M9N</th>
<th>D-M9P</th>
<th>D-M9B</th>
</tr>
</thead>
<tbody>
<tr>
<td>Electrical entry direction</td>
<td>In-line</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wiring type</td>
<td>3-wire</td>
<td></td>
<td>2-wire</td>
</tr>
<tr>
<td>Output type</td>
<td>NPN</td>
<td>PNP</td>
<td></td>
</tr>
<tr>
<td>Applicable load</td>
<td>IC circuit, Relay, PLC</td>
<td>24 VDC relay, PLC</td>
<td></td>
</tr>
<tr>
<td>Power supply voltage</td>
<td>5, 12, 24 VDC (4.5 to 28 V)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Current consumption</td>
<td>10 mA or less</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Load voltage</td>
<td>28 VDC or less</td>
<td></td>
<td>24 VDC (10 to 28 VDC)</td>
</tr>
<tr>
<td>Load current</td>
<td>40 mA or less</td>
<td></td>
<td>2.5 to 40 mA</td>
</tr>
<tr>
<td>Internal voltage drop</td>
<td>0.8 V or less</td>
<td></td>
<td>4 V or less</td>
</tr>
<tr>
<td>Leakage current</td>
<td>100 µA or less at 24 VDC</td>
<td></td>
<td>0.8 mA or less</td>
</tr>
<tr>
<td>Indicator light</td>
<td>Red LED illuminates when ON.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<p>|</p>
<table>
<thead>
<tr>
<th>Lead wire length (m)</th>
<th>0.5</th>
<th>3</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>D-M9N</td>
<td>8</td>
<td>41</td>
<td>68</td>
</tr>
<tr>
<td>D-M9P</td>
<td>8</td>
<td>41</td>
<td>68</td>
</tr>
<tr>
<td>D-M9B</td>
<td>7</td>
<td>38</td>
<td>63</td>
</tr>
</tbody>
</table>

Dimensions

For details about certified products conforming to international standards, visit us at www.smcworld.com.

1) Refer to page 16 for solid state switch common specifications.
2) Refer to page 16 for lead wire lengths.

Note 1) Fix the switch with the existing screw installed on the switch body. The switch may be damaged if a screw other than the one supplied, is used.

Note 2) For details about certified products conforming to international standards, visit us at www.smcworld.com.
Directional Control Driver for Electric Cylinder

Series **LC3F2**

Able to control the stroke with only ON/OFF signals
- Directional control driver like a solenoid valve

Able to set thrust arbitrarily.
- Thrust can be adjusted by adjustment trimmer

Able to control with only 3 different types of input signals
- ① Directional instruction ② Thrust selection ③ Output ON/OFF

Can be operated manually
- Maintenance performance for wiring check has been improved

### Product Specifications

<table>
<thead>
<tr>
<th>Model</th>
<th>LC3F212-5A3</th>
<th>LC3F212-5A5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power supply voltage</td>
<td>24 VDC ± 10%</td>
<td>Max. 2.3 A</td>
</tr>
<tr>
<td>Front side label color</td>
<td>Gray</td>
<td>Blue</td>
</tr>
<tr>
<td>Input signal</td>
<td>Photocoupler input 24 VDC ±10% Max. 8 mA/point</td>
<td></td>
</tr>
<tr>
<td>Selection of thrust</td>
<td>100% or set value (setting range 10 to 70% F.S.)</td>
<td></td>
</tr>
<tr>
<td>Operating temperature range</td>
<td>+5 to 40°C</td>
<td></td>
</tr>
<tr>
<td>Operating humidity range</td>
<td>35 to 85% Rh (with no condensation)</td>
<td></td>
</tr>
<tr>
<td>Environment</td>
<td>Indoor (Direct sunlight should be avoided.) No corrosive gas, inflammable gas, oil mist or dust particle</td>
<td></td>
</tr>
<tr>
<td>Display LED</td>
<td>POWER, A-PHASE, OFF, SET</td>
<td></td>
</tr>
<tr>
<td>Weight</td>
<td>145 g</td>
<td></td>
</tr>
</tbody>
</table>

19
Series LC3F2
Directional Control Driver for Electric Cylinder

How to Order

LC3 F2 12 5 A3 B

Series F2: Small sized DC motor driver
Power supply 24 VDC
Applicable motor
A3 DC motor (cylinder size 3)
A5 DC motor (cylinder size 5)

Housing set (Connector set)
A Housing for CN1, 2, 3 (connector) & contact (connector pin) are included as an accessory.
B Nothing included.

Option

- Cable for power supply terminal
  LC3F2 1 C1 02 1
  Cable type
  C1 Cable for CN1 power supply terminal
  Cable length
  01 1 m
  02 2 m

- Cable for control terminal
  LC3F2 1 C2 02 1
  Cable type
  C2 Cable for CN2 control terminal
  Cable length
  01 1 m
  02 2 m

- Cable for motor output terminal
  LC3F2 1 C3 02 1
  Cable type
  C3 Cable for CN3 motor output terminal
  Cable length
  02 2 m
  05 5 m

- Housing set (Connector set)
  LC3F2 1 C0
  Housing for power supply terminal (Connector)
  1 pc. VHR-3N: J.S.T. Mfg Co., Ltd.
  Housing for control terminal (Connector)
  1 pc. VHR-4N: J.S.T. Mfg Co., Ltd.
  Housing for motor output terminal (Connector)
  1 pc. VHR-2N: J.S.T. Mfg Co., Ltd.
  Contact (Connector pin)
  12 pcs. BVH-21T-P1.1: J.S.T. Mfg Co., Ltd.

Caution

- Do not apply repetitive bending or pulling stress to the cable.
  Wiring with repetitive bending or pulling stress to the cable will likely cause the cable to break.
- In the event of crimping the contact (connector pin) and wire, use the specific tools as well as the recommended cable.
  Crimping tool: YC-160R (J.S.T. Mfg Co., Ltd.)
  Pulling tool: EJ-NV (J.S.T. Mfg Co., Ltd.)
  Recommended cable connection (common for individual cable) AWG21 (0.5 mm²), Insulated wire O.D. 1.7 to 3.0 mm with shield, Heat resistance is more than 80°C.
  Maximum cable length
  CN1 cable for power supply terminal 2 m
  CN2 cable for control terminal 2 m
  CN3 cable for motor output terminal 5 m
- Shield is attached with an optional cable for the LC3F2 series.
  When grounding a shield, remove the sheath and use a metal U-clip or P-clip.
**Applicable Cylinder Table**

<table>
<thead>
<tr>
<th>Cylinder part no.</th>
<th>Applicable directional control driver</th>
</tr>
</thead>
<tbody>
<tr>
<td>L-Z-3-□-□-□-□-□-□-□-□-□-□-□-□-□</td>
<td>LC3F212-5A3-□</td>
</tr>
<tr>
<td>L-Z-5-□-□-□-□-□-□-□-□-□-□-□-□-□-□</td>
<td>LC3F212-5A5-□</td>
</tr>
</tbody>
</table>

**Dimensions**

How to Mount

Mount the directional control driver vertically against the wall, using two mounting screw holes, so the front side (on which its adjustment trimmer and manual switch are located) is facing to an operator.

Applicable mounting screw: M3 (2 pcs.) [to be supplied by customer]

- **How to mount a protection grounding terminal**
  - Cross recessed bind screw (Accessory) M3 x 4 1 pc.
  - Spring washer Nominal 3 1 pc.
  - Tooth lock washer (A) Nominal 3 1 pc.

Components for mounting the protection grounding terminal are provided together with the product.
Wiring Example

There is no emergency stop function or power supply switch in the directional control driver. Please be sure to provide an emergency stop and power supply insulation (insulator) device as a total machine equipment, referencing the above wiring examples. Also, please be sure to turn off the power supply for the whole equipment prior to wiring the directional control driver.

**CN1 Power Supply Terminal**

<table>
<thead>
<tr>
<th>Pin no.</th>
<th>Terminal</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>FG</td>
<td>Frame ground</td>
</tr>
<tr>
<td>2</td>
<td>DC (+)</td>
<td>Driver power supply (+24 V)</td>
</tr>
<tr>
<td>3</td>
<td>DC (-)</td>
<td>Driver power supply (0 V)</td>
</tr>
</tbody>
</table>

**CN3 Motor Output Terminal**

<table>
<thead>
<tr>
<th>Pin no.</th>
<th>Terminal</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>OUTA</td>
<td>Motor output A (Blue wire)</td>
</tr>
<tr>
<td>2</td>
<td>OUTB</td>
<td>Motor output B (Red wire)</td>
</tr>
</tbody>
</table>

**CN2 Control Terminal**

<table>
<thead>
<tr>
<th>Pin no.</th>
<th>Terminal</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>COM</td>
<td>Motor output</td>
</tr>
<tr>
<td>2</td>
<td>ON</td>
<td>Output ON command input</td>
</tr>
<tr>
<td>3</td>
<td>SET</td>
<td>Adjusted thrust command input</td>
</tr>
<tr>
<td>4</td>
<td>A-PHASE</td>
<td>Traveling direction command input</td>
</tr>
</tbody>
</table>

**Caution**

There is no emergency stop function or power supply switch in the directional control driver. Please be sure to provide an emergency stop and power supply insulation (insulator) device as a total machine equipment, referencing the above wiring examples. Also, please be sure to turn off the power supply for the whole equipment prior to wiring the directional control driver.

**How to wire**

For System Chart, refer to Features 1.
### Description of Each Part and its Function

<table>
<thead>
<tr>
<th>Category</th>
<th>Description</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thruster trimmer</td>
<td>Thrust changes through adjustment.</td>
<td></td>
</tr>
<tr>
<td>POWER</td>
<td>Light illuminates when power is supplied.</td>
<td></td>
</tr>
<tr>
<td>A-PHASE</td>
<td>Light illuminates by A-PHASE command. (Travelling to the retracted side when illuminated)</td>
<td></td>
</tr>
<tr>
<td>OFF</td>
<td>Light illuminates when turning OFF. (No motor output is generated when illuminated.)</td>
<td></td>
</tr>
<tr>
<td>SET</td>
<td>Light illuminates by SET command. (Thrust set by the thrust adjustment trimmer, when illuminated, will be outputted.)</td>
<td></td>
</tr>
<tr>
<td>A-PHASE</td>
<td>A-PHASE command while pressing (Travelling to the retracted side)</td>
<td></td>
</tr>
<tr>
<td>ON</td>
<td>ON command while pressing (Motor output will be generated.)</td>
<td></td>
</tr>
<tr>
<td>SET</td>
<td>SET command while pressing (Thrust set by the thrust adjustment trimmer will be outputted.)</td>
<td></td>
</tr>
</tbody>
</table>

### Timing Chart

- **ON**
- **OFF**
- **SET**
- **A-PHASE**

#### Thrust
- **(Retracted side)** (Note) 100%
- **(Extended side)** (Note) 0%

#### CN2 Control Terminal

<table>
<thead>
<tr>
<th>Pin no.</th>
<th>Terminal</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>COM</td>
<td>Common terminal</td>
</tr>
<tr>
<td>2</td>
<td>ON</td>
<td>Output ON command input</td>
</tr>
<tr>
<td>3</td>
<td>SET</td>
<td>Adjusted thrust command input</td>
</tr>
<tr>
<td>4</td>
<td>A-PHASE</td>
<td>Traveling direction command input</td>
</tr>
</tbody>
</table>

- **ON**: Motor output
- **OFF**: No motor output
- **ON**: Adjusted thrust
- **OFF**: 100% thrust (Max. thrust)
- **ON**: A-PHASE (Retracted side) (Note)
- **OFF**: B-PHASE (Extended side) (Note)

*Note* For the travelling direction (retracted, extended side), refer to the dimensions in page 4, 6, 10 and 11.

*Note* For the travelling direction (retracted, extended side), refer to the dimensions in page 4, 6, 10 and 11.
Electric Cylinders

Safety Instructions

These safety instructions are intended to prevent a hazardous situation and/or equipment damage. These instructions indicate the level of potential hazard by labels of "Caution", "Warning" or "Danger". To ensure safety, be sure to observe ISO 10218-1992 \(^{Note 1}\), JIS B 8433-1993 \(^{Note 2}\) and other safety practices.

**Caution** : Operator error could result in injury or equipment damage.

**Warning** : Operator error could result in serious injury or loss of life.

**Danger** : In extreme conditions, there is a possibility of serious injury or loss of life.

---

\(^{Note 1}\) ISO 10218-1992: Manipulating industrial robots-Safety

\(^{Note 2}\) JIS B 8433-1993: Manipulating industrial robots--Safety

---

**Warning**

1. The compatibility of the electric cylinder with an application should be examined by the system planner, or by the person who determines the specifications.
   
   Since the products specified here are used in various operating conditions, their compatibility with a specific system must be based on either specifications, post analysis and/or tests to meet a specific requirement. The expected performance and safety assurance is the responsibility of the person who has determined the compatibility between the cylinder and the system. This person should continuously review the suitability of all items specified, referring to the latest catalog information with consideration towards any possible equipment failure when configuring the system.

2. Only trained personnel should operate pneumatically operated machinery and equipment.
   
   Compressed air can be dangerous if handled incorrectly. Assembly, handling or repair of an electric cylinder should be performed by a trained and experienced operator.

3. Do not service machinery/equipment or attempt to remove components until safety is confirmed.
   
   1. Inspection and maintenance of machinery/equipment should only be performed after confirmation of safe locked-out control positions.
   
   2. When equipment will be removed, confirm the safety process as mentioned above, and shut off the power supply for this equipment.
   
   3. Before machinery/equipment is restarted, confirm that safety measures are in effect.

4. Contact SMC if the product will be used in any of the following conditions:
   
   1. Conditions and environments beyond the given specifications, or if product is used outdoors.
   
   2. Installation on equipment in conjunction with atomic energy, medical equipment, food and beverages, or safety equipment.
   
   3. An application which has the possibility of having negative effects on people, property, or animals, requiring special safety analysis.

5. Review and confirm the product’s documentation thoroughly before using the product, or contact our distributors, or SMC for confirmation for a problem free application.

6. Use the product after thoroughly reviewing and confirming the precautions in this catalog.

7. Some products in this catalog are for particular applications and sites only. Check and confirm with the distributor or SMC.
Electric Cylinder Precautions 1
Be sure to read this before handling.

General

Caution on Handling

⚠️ Caution
1. In order to ensure proper operation, be certain to read the instruction manual carefully. As a rule, handling or usage/operation other than those contained in the instruction manual are prohibited.
2. If the cylinder will be used in an environment where it will be exposed to chips, dust, cutting oil (water, liquids), etc., a cover or other protection should be provided.
3. Operate with cables secured. Avoid bending cables at sharp angles where they enter the cylinder, and also be sure that cables do not move easily.

Caution on Design

⚠️ Warning
1. In cases where dangerous conditions may result from power failure or malfunction of the product, install safety equipment to prevent damage to machinery and human injury. Consideration must also be given to drop prevention with regard to suspension equipment and lifting mechanisms.
2. Consider possible loss of power sources.
   Take measures to protect against human injury and machine damage in the event that there is a loss of air pressure, electricity or hydraulic power.
3. Consider emergency stops.
   Design so that human injury and/or damage to machinery and equipment will not be caused when machinery is stopped by a safety device under abnormal conditions such as a power outage or a manual emergency stop.
4. Consider the action when operation is restarted after an emergency stop or abnormal stop.
   Design the machinery so that human injury or equipment damage will not occur upon restart of operation.

Selection

⚠️ Warning
1. Confirm the specifications.
   The products in this catalog should not be used outside of the range of specifications, since this may cause damage malfunction, etc. (Refer to the specifications.)

Mounting

⚠️ Caution
1. Make sure that cables are not caught by cylinder movement.
2. Do not use in locations where there is vibration or impact shock. Contact SMC before using in this kind of environment, as damage may result.
3. Give adequate consideration to the arrangement of wiring, etc., when mounting. If wiring is forced into inappropriate arrangement, this may lead to breaks in the wiring and result in malfunction.

Operating Environment

⚠️ Caution
1. Avoid use in the following environments.
   1. Locations with a lot of debris or dust, or where chips may enter.
   2. Locations where the ambient temperature exceeds the operating temperature range specified in each model. (Refer to the specifications.)
   3. Locations where the ambient humidity exceeds the operating humidity range specified in each model. (Refer to the specifications.)
   4. Locations where corrosive or combustible gases are generated.
   5. Locations where strong magnetic or electric fields are generated.
   6. Locations where direct vibration or impact shock, etc., will be applied to the cylinder unit.
   7. Locations where a lot of dusts, water drops and oil drops are applied to a product.

Maintenance

⚠️ Warning
1. Perform a maintenance according to the procedures indicated in the instruction manual. If handled improperly, malfunction and damage of machinery or equipment may occur.
2. Removal of equipment
   When equipment is removed, first confirm that measures are in place to prevent dropping or runaway of driven objects, etc., and then proceed after shutting off the electric power. When starting up again, proceed with caution after confirming that conditions are safe.

Grounding

⚠️ Warning
1. Be sure to ground an electric cylinder.
2. Dedicated grounding should be used as much as possible. Grounding should be to a type 3 ground. (Ground resistance of 100 \( \Omega \) or less.)
3. Grounding should be as close as possible to the electric cylinder, and the ground wires should be as short as possible.
Electric Cylinder Precautions 2
Be sure to read this before handling.

---

**Caution on Design**

**Warning**
1. There is a possibility of dangerous sudden action by cylinders if sliding parts of machinery are twisted due to external forces, etc. In such cases, human injury may occur, e.g., by catching hands or feet in the machinery, or damage to the machinery itself may occur. Therefore, the machine should be adjusted for smooth operation and designed to avoid such dangers.

2. A protective cover is recommended to minimize the risk of human injury. If a driven object and moving parts of a cylinder pose a danger of human injury, design the structure to avoid contact with the human body.

3. Securely tighten all stationary parts and connected parts of cylinders so that they will not become loose. Avoid use in locations where direct vibration or impact shock, etc., will be applied to the body of the cylinder.

**Caution**
9. In case several persons are doing the job, determine the procedure, signs, measures against abnormality and restarting measures in advance. Then let the person who is not doing the job supervise that job.

**Operation**

1. Conduct the following inspection before cylinder/directional control driver is operated.
   a) Confirm that the power supply line or each signal line for cylinder/directional control driver is not broken.
   b) Confirm that the power supply line or each signal line for cylinder/directional control driver is not loosened.
   c) Confirm that the cylinder/directional control driver is not mounted loosely.
   d) Confirm that the cylinder/directional control driver is operated correctly.
   e) Confirm the function of the emergency stop.

2. Take measures such as installing a fence, etc., to prevent any person from entering the operational area of the cylinder/directional control driver and related equipment.

3. If a person should enter an area as mentioned above 2., take measures to ensure that the emergency stop is controlled by a sensor, etc.

4. In case the cylinder/directional control driver is stopped by abnormalities, take necessary measures to prevent danger from related equipment.

5. In case of abnormalities of related equipment, take necessary measures to prevent danger from a cylinder/directional control driver.

6. Fix the cylinder’s fixing part and connecting part securely. If the cylinder is used at a high frequency or in a location with a large amount of vibration, fix securely using adhesives to prevent it from loosening.

---

**Caution on Handling**

**Warning**

1. The cylinder can be used with a load directly applied to it, as long as it is within the allowable range. However, it is necessary to design an appropriate connecting method and use careful alignment when a load with external support and guide mechanisms is connected. The longer the stroke is, the larger the variation in the axial center becomes. Therefore, devise a connection method to absorb the variation.

2. The product can be used without lubrication. In case the product is lubricated, special grease is required. Contact the distributor or SMC.

**Operation**

1. Do not use until you verify that the equipment can operate properly.

2. The product should be mounted and operated after thoroughly reading the instruction manual and understanding its contents.

3. Do not dent, scratch or cause other damage to the body and table mounting surfaces. This may cause a loss of parallelism in the mounting surfaces, looseness in the guide unit, an increase in sliding resistance or other problems.

4. When attaching a workpiece, do not apply strong impact shock or a large moment. If an outside force exceeding the allowable moment is applied, this may cause looseness in the guide unit, an increase in sliding resistance or other problems.

5. When connecting a load having an external support or guide mechanism, be sure to select a suitable connection method and perform careful alignment.

6. Fix the cylinder’s fixing part and connecting part securely. If the cylinder is used at a high frequency or in a location with a large amount of vibration, fix it securely using adhesives to prevent it from loosening.

---

**Mounting**

**Caution**

1. Find the cylinder and check that the equipment can operate properly.

2. The product should be mounted and operated after thoroughly reading the instruction manual and understanding its contents.

3. Do not dent, scratch or cause other damage to the body and table mounting surfaces. This may cause a loss of parallelism in the mounting surfaces, looseness in the guide unit, an increase in sliding resistance or other problems.

4. When attaching a workpiece, do not apply strong impact shock or a large moment. If an outside force exceeding the allowable moment is applied, this may cause looseness in the guide unit, an increase in sliding resistance or other problems.

5. When connecting a load having an external support or guide mechanism, be sure to select a suitable connection method and perform careful alignment.

6. Fix the cylinder’s fixing part and connecting part securely. If the cylinder is used at a high frequency or in a location with a large amount of vibration, fix it securely using adhesives to prevent it from loosening.
Directional Control Driver Precautions 1

Be sure to read this before handling.

---

**Caution on Handling**

**Warning**
1. Never touch the directional control driver inside. It will likely lead to an electrical shock or other trouble.
2. Use only the designated combination between motor and directional control driver.

**Caution**
1. Do not disassemble and modify. It may result in the trouble, malfunction, fire, etc.
2. Do not touch for a while when being energized or after cutting off the power source because it is high temperature.
3. If a fire or danger against the human being is expected by abnormal heat generation of the product, emitting fume and catching on fire, etc., cut off the power supply for the main body and the system immediately.

---

**Power Supply**

1. In cases where voltage fluctuations greatly exceed the required voltage, a constant voltage transformer, etc., should be used to allow operation within the required range.
2. Use a power supply that has low noise between lines and between power and ground. In cases where noise is high, an isolation transformer should be used.
3. The power supply line and the interface power supply line must be wired separately in different systems.
4. To prevent surges from lightning, connect a varistor for lightning. Ground the surge absorber for lightning separately from the grounding of the directional control driver.

---

**Grounding**

1. Be sure to carry out grounding in order to ensure the noise tolerance of the directional control driver.
2. Dedicated grounding should be used as much as possible. Grounding should be to a type 3 ground. (Ground resistance of 100 $\Omega$ or less.)
3. Grounding should be as close as possible to the directional control driver, and the ground wires should be as short as possible.
4. In the unlikely event that malfunction is caused by the ground, disconnected it from the ground.

---

**Mounting**

1. Mount the directional control driver on incombustible materials. Mounting on combustible materials directly or mounting closely to it may lead to a fire.
2. Consider the cooling period, so that the operating temperature of main body should be within the range of specifications. Also, allow enough distance from each side of the main body, construction and the parts. Cooling should be considered, so the surface temperature of a heat sink should not be more than 50°C even though the temperature is within the operating range.
3. Avoid placing with large-sized solenoid contact apparatus or vibrating source such as no fuse insulator and then make a separate panel or mount in the distance.
4. Mounting should enable the connectors to be inserted or removed after installation.
5. If there are concave or convex or distorted parts on the mounting face of a directional control driver, an unreasonable force can be applied to the frame or case, which can cause trouble. Mount on the flat face.

---

**Wiring**

1. Adjustment, installation, or wiring changes should be conducted after power supply to this product is turned off. Otherwise, there is a possibility of an electrical shock.
2. Connect the housing securely.
3. Treat the noise securely. If the noise is at the same wavelength as the signal lines, it will lead to malfunction. As a countermeasure, separate the high and low electrical lines and shorten the length of wiring, etc.
4. When using a cable made by oneself, confirm the electric wire is of a proper gauge as mentioned in the instruction manual and it is not affected by a noise before using.

---

Back page 4
### Wiring

**Warning**

1. **Avoid repeatedly bending and/or stretching the cables.**
   - Repeatedly applying bending stress and/or stretching force to the cables may result in broken lead wires.
2. **Avoid incorrect wiring.**
   - Depending on the type of incorrect wiring, the directional control driver may be damaged.
3. **Perform wiring when the power is turned off.**
   - The directional control driver may be damaged and malfunction.
4. **Do not wire with power lines or high voltage lines.**
   - Conduct wiring for a directional control driver separately from power lines or high voltage lines to avoid interference from the noise or surge of the power lines or high voltage lines. This may result in malfunction.
5. **Confirm that the wiring is properly insulated.**
   - Be certain that there is no faulty wiring insulation (contact with other circuits, improper insulation between terminals, etc.) because the directional control driver may be damaged due to excessively applied voltage or current flow to it.

### Adjustment and Operation

**Warning**

1. **Do not short the loads.**
   - Short on the load of the directional control driver indicates an error, but it may cause over current and damage the directional control driver.
2. **Do not operate or conduct any settings with wet hands.**
   - An electric shock may result from wet hands.
3. **When operating the manual switch, avoid making contact with the workpiece.**
   - Contact with the workpiece may cause injury.

### Operating Environment

**Warning**

1. **Do not use in an environment subjected to temperature cycle.**
   - If used in an environment where temperature cycling occurs, other than the usual temperature change, the internal directional control driver may be adversely effected.
2. **Do not use in a place that has excessive electrical surge generation.**
   - When there are units (solenoid type lifter, high frequency induction furnace, motor, etc.) which generate a large amount of surge in an area around the directional control driver, deterioration or damage may occur to the internal circuit elements of the directional control driver. Avoid sources of surge generation and crossed lines.
3. **Select a product type that has built-in surge absorbing elements for a load, such as relays and solenoid valves employed for driving voltage generating load directly.**
4. **Avoid use in the following environments.**
   1. Locations with a lot of debris or dust, or where chips may enter.
   2. Locations where the ambient temperature exceeds the operating temperature range specified in each model. (Refer to the specifications.)
   3. Locations where the ambient humidity exceeds the operating humidity range specified in each model. (Refer to the specifications.)
   4. Locations where corrosive or combustible gases are generated.
   5. Locations where strong magnetic or electric fields are generated.
   6. Locations where direct vibration or impact shock, etc., will be applied to the cylinder unit.
   7. Locations where a lot of dusts, water drops and oil drops are applied to a product.

### Maintenance

**Warning**

1. **Periodically perform a maintenance of the product.**
   - Confirm that the piping and bolts are securely tightened. Unintentional malfunction of a system’s components may occur as a result of a cylinder malfunction.
2. **Do not disassemble, modify (including change of printed circuit board) or repair.**
   - Disassembly or modification may result in injury or failure.

**Caution**

1. **Confirm the range of movement of a workpiece (a slider) before connecting the driving power supply or turning on the switch.**
   - The movement of the work may cause an accident.
Caution on Design and Selection

⚠️ Warning

1. **Conduct operation at regulated voltage.**
   The product may not function correctly or the directional control driver section may be damaged if used with any other voltage than the specified regulated voltage.

2. **Operate within the limit of the specification range.**
   If operated outside of the specification range, there is a possibility of fire, malfunction, and or cylinder damage. Operate after confirming the required specifications.

3. **To prevent any damage by product failure or malfunction, plan and construct a backup system beforehand, such as multiplexing the components and equipment, employing failure free planning, etc.**

4. **Secure the space for maintenance.**
   When planning, consider the space to be required for product checkup and maintenance.

5. **Provide a protective cover when there is a risk of human injury.**
   If a driven object and or moving parts of a cylinder pose a danger to human injury, design the structure to avoid contact with the human body.
1. If an electric cylinder with DC motor should be rotated by the larger external force than the generated thrust, the reverse inrush voltage generated may cause adverse effects on the electric cylinders directional control driver and result in malfunction or damage to the product.

Example:
- Do not push or pull a cylinder rod, applying a larger load than the generated thrust. (Please use caution if the generated thrust should be switched over between a high thrust and a low thrust.)

Caution on Design and Operation
1. Confirm the specifications.
Read the specifications carefully and use this product appropriately. The product may be damaged or malfunction if it is used outside the range of specifications of current load, voltage, temperature or impact.

2. Use caution when multiple actuators are used and close to each other.
When two or more auto switch actuators are lined up in close proximity to each other, magnetic field interference may cause the switches to malfunction. Maintain a minimum cylinder separation of 40 mm.

3. Pay attention to the length of time that a switch is ON at an intermediate stroke position.
When an auto switch is placed at an intermediate position of the stroke and a load is driven at the time the piston passes, the auto switch will operate, but if the speed is too great the operating time will be shortened and the load may not operate properly. The maximum detectable piston speed is:

\[ V (\text{mm/s}) = \frac{\text{Auto switch operating range (mm)}}{\text{Time load applied (ms)}} \times 1000 \]

4. Keep wiring as short as possible.
- **Solid state switch**
Although wire length should not affect switch function, use a wire 100 m or shorter.

5. Take note of the internal voltage drop of the switch.
- **Solid state switch**
Generally, the internal voltage drop will be greater with a 2-wire solid state auto switch than with a reed switch. Take the same precautions as in 1).
Also, note that a 12 VDC relay is not applicable.

6. Pay attention to leakage current.
- **Solid state switch**
With a 2-wire solid state auto switch, current (leakage current) flows to the load to operate the internal circuit even when in the OFF state.

   \[ \text{Operating current of load (OFF condition)} > \text{Leakage current} \]

If the criteria given in the above formulas are not met, it will not reset correctly (stays ON). Use a 3-wire switch if this specification will not be satisfied.
Moreover, leakage current flow to the load will be "n" times larger when "n" auto switches are connected in parallel.

7. Do not use a load that generates surge voltage.
- **Solid state switch**
Although a zener diode for surge protection is connected at the output side of a solid state auto switch, damage may still occur if the surge is applied repeatedly. When a load, such as a relay or solenoid, which generates surge is directly driven, use a type of switch with a built-in surge absorbing element.

8. Cautions for use in an interlock circuit
When an auto switch is used for an interlock signal requiring high reliability, devise a double interlock system to avoid trouble by providing a mechanical protection function, or by also using another switch (sensor) together with the auto switch. Also perform periodic maintenance and confirm proper operation.

9. Ensure sufficient clearance for maintenance activities.
When designing an application, be sure to allow sufficient clearance for maintenance and inspections.
Auto Switch Precautions 2
Be sure to read this before handling.

Mounting & Adjustment

⚠️ Warning

1. Do not drop or bump.
Do not drop, bump or apply excessive impacts (300 m/s² or more for reed switches and 1000 m/s² or more for solid state switches) while handling. Although the body of the switch may not be damaged, the inside of the switch could be damaged and cause a malfunction.

2. Do not carry an actuator by the auto switch lead wires.
Never carry a cylinder (actuator) by its lead wires. This may not only cause broken lead wires, but it may cause internal elements of the switch to be damaged by the stress.

3. Mount switches using the proper fastening torque.
When a switch is tightened beyond the range of fastening torque, the mounting screws, mounting bracket or switch may be damaged. On the other hand, tightening below the range of fastening torque may allow the switch to slip out of position.

4. Mount a switch at the center of the operating range.
Adjust the mounting position of an auto switch so that the piston stops at the center of the operating range (the range in which a switch is ON).
(The mounting position shown in a catalog indicates the optimum position at stroke end.) If mounted at the end of the operating range (around the borderline of ON and OFF), operation will be unstable.

⚠️ Caution

1. Fix the switch with appropriate screw installed on the switch body. If using other screws, switch may be damaged.

Wiring

⚠️ Warning

1. Avoid repeatedly bending or stretching lead wires.
Broken lead wires will result from applying bending stress or stretching force to the lead wires.

2. Be sure to connect the load before power is applied.

<2-wire type>
If the power is turned ON when an auto switch is not connected to a load, the switch will be instantly damaged because of excess current.

3. Confirm proper insulation of wiring.
Be certain that there is no faulty wiring insulation (contact with other circuits, ground fault, improper insulation between terminals, etc.). Damage may occur due to excess current flow into a switch.

4. Do not wire with power lines or high voltage lines.
Wire separately from power lines or high voltage lines, avoiding parallel wiring or wiring in the same conduit with these lines. Control circuits, including auto switches, may malfunction due to noise from these other lines.

5. Do not allow short circuit of loads.

<Solid state switch>
Model D-M9□ and all models of PNP output type switches do not have built-in short circuit prevention circuits. If loads are short circuited, the switches will be instantly damaged, as in the case of reed switches.
Take special care to avoid reverse wiring with the power supply line (brown) and the output line (black) on 3-wire type switches.

6. Avoid incorrect wiring.

<Solid state switch>
1) If connections are reversed on a 2-wire type switch, the switch will not be damaged if protected by a protection circuit, but the switch will always stay in an ON state. However, it is still necessary to avoid reversed connections, since the switch could be damaged by a load short circuit in this condition.

2) If connections are reversed (power supply line + and power supply line –) on a 3-wire type switch, the switch will be protected by a protection circuit. However, if the power supply line (+) is connected to the blue wire and the power supply line (–) is connected to the black wire, the switch will be damaged.

⚠️ Lead wire color changes
Lead wire colors of SMC auto switches have been changed in order to meet NECA Standard 0402 for production beginning September, 1996 and thereafter. Please refer to the tables provided.

<table>
<thead>
<tr>
<th>2-wire</th>
<th>3-wire</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output (+)</td>
<td>Power supply (+)</td>
</tr>
<tr>
<td>Red</td>
<td>Red</td>
</tr>
<tr>
<td>Output (–)</td>
<td>Power supply GND</td>
</tr>
<tr>
<td>Black</td>
<td>Black</td>
</tr>
<tr>
<td>Output</td>
<td>White</td>
</tr>
</tbody>
</table>

*D-M9□ does not have built-in short circuit protection circuit. Be aware that if the power supply connection is reversed (e.g. (+) power supply wire and (–) power supply wire connection is reversed), the switch will be damaged.*
Auto Switch Precautions 3
Be sure to read this before handling.

Wiring

⚠️ Caution
5. When the cable sheath is stripped, confirm the stripping direction. The insulator may be split or damaged depending on the direction. (D-M9□ only)

Recommended Tool

<table>
<thead>
<tr>
<th>Model name</th>
<th>Model no.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wire stripper</td>
<td>D-M9N-SWy</td>
</tr>
</tbody>
</table>

※ Stripper for a round cable (ø2.0) can be used for a 2-wire type cable.

Operating Environment

⚠️ Warning
7. Do not use in an area where surges are generated.

<Solid state switch>
When there are units (solenoid type lifter, high frequency induction furnace, motor, etc.) which generate a large amount of surge in the area around actuators with solid state auto switches, this may cause deterioration or damage to the switches. Avoid sources of surge generation and crossed lines.

8. Avoid accumulation of iron debris or close contact with magnetic substances.
When a large amount of ferrous debris such as machining chips or spatter is accumulated, or a magnetic substance (something attracted by a magnet) is brought into close proximity with an auto switch actuator, it may cause the auto switch (actuator) to malfunction due to a loss of the magnetic force inside the actuator.

Maintenance

⚠️ Warning
1. Perform the following maintenance periodical-ly in order to prevent possible danger due to unexpected auto switch malfunction.

1) Securely tighten switch mounting screws. If screws become loose or the mounting position is dislocat-ed, retighten them after readjusting the mounting position.
2) Confirm that there is no damage to lead wires. To prevent faulty insulation, replace switches or repair lead wires, etc., if damage is discovered.

Other

⚠️ Warning
1. Consult with SMC concerning water resistance, elasticity of lead wires, usage at welding sites, etc.